# (RoHS) RoHS-Compliant Induction Motors

W 9

15 W

25 W



#### Features

#### Optimal for Uni-Directional Continuous Operation

Induction motors are optimal for uni-directional continuous operation such as a conveyor system.

#### Safety Standards and CE Marking

Standards	Certification Body	CE Marking					
UL 1004 UL 2111		ци Е64199 (1 W∼6 W Туре)					
CSA C22.2 No.100 CSA C22.2 No.77	UL	E64197 (15 W~150 W Type)					
EN 60950-1 EN 60034-1 EN 60034-5 IEC 60664-1		Conform to EN/IEC Standards	Low Voltage Directives				
GB 12350	CQC	2005010401150786 (Single-Phase 1 W, 3 W Type) 2003010401091525 (Single-Phase 6 W Type) 2003010401091527 (Three-Phase 6 W Type) 2003010401091522 (Single-Phase 15 W~90 W Type) 2003010401091520 (Three-Phase 25 W~90 W Type) 2005010401150785 (2-Pole, High-Speed Type, Single-Phase 40 W~150 W Type) 2005010401150788 (2-Pole, High-Speed Type, Three-Phase 60 W~150 W Type)					

• When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

• The following products are not applicable to the table above

#### 4IK25GN-UT4, 4IK25A-UT4, 5IK40GN-UT4, 5IK40A-UT4, 5IK60GE-UT4F, 5IK60A-UT4F, 5IK90GE-UT4F, 5IK90A-UT4F

Standards	Certification Body	Standards File No.	CE Marking								
EN 60950-1 EN 60034-1 EN 60034-5 IEC 60034-11	TÜV Rheinland	R50079501	Low Voltage Directives								

# System Configuration



• The system configuration shown above is an example. Other configurations are available.

# Product Number Code

Motor

# 5 I K 40 GN - CW 2 T E

$\bigcirc$	2 3 4											
1	Motor Frame Size	: 42 mm <b>2</b> : 60 mm <b>3</b> : 70 mm <b>4</b> : 80 mm <b>5</b> : 90 mm										
2	Motor Type	I: Induction Motor										
3	Series	K Series										
4	Output Power (W)	(Example) <b>40</b> : 40 W										
5	Motor Shaft Type	GN: GN Type Pinion Shaft GE: GE Type Pinion Shaft A: Round Shaft										
6	Power Supply Voltage/ Number of Poles	AW: Single-Phase 100 VAC, 110/115 VAC 4-Pole       BW: Single-Phase 100 VAC, 110/115 VAC 2-Pole       CW: Single-Phase 200 VAC, 220/230 VAC 4-Pole         DW: Single-Phase 200 VAC, 220/230 VAC 2-Pole       SW: Three-Phase 200/220/230 VAC 4-Pole       Tw: Three-Phase 200/220/230 VAC 2-Pole         U: Three-Phase 400 VAC 4-Pole       SW: Three-Phase 200/220/230 VAC 4-Pole       Tw: Three-Phase 200/220/230 VAC 2-Pole										
0	2, 3: RoHS-Compliant											
8	T, T4, T4F: Terminal Bo	х Туре										
9	Included Capacitor	J: For Single-Phase 100 VAC, 200 VAC U: For Single-Phase 110/115 VAC E: For Single-Phase 220/230 VAC Blank: Three-Phase Type										

• The J, U and E at the end of the model name indicate that the unit includes a capacitor. These letters are not listed on the motor nameplate. When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

(Example) Model: 5IK40GN-CW2E -> Motor nameplate and product approved under various safety standards: 5IK40GN-CW2

#### Gearhead

5	GN	50	S
1	2	3	(4)
1	Gearhead F	rame Size	<b>0</b> : 42 mm <b>2</b> : 6
2	Type of Pin	ion	GN: GN Type

1	Gearhead Frame Size	<b>D</b> : 42 mm <b>2</b> : 60 mm <b>3</b> : 70 mm <b>4</b> : 80 mm <b>5</b> : 90 mm							
2	Type of Pinion	;N: GN Type Pinion GE: GE Type Pinion							
3	Gear Ratio	(Example) 50: Gear Ratio of 1:50 10X denotes the decima	ample) <b>50</b> : Gear Ratio of 1:50 <b>10X</b> denotes the decimal gearhead of gear ratio 1:10						
4	<b>GN</b> Type Pinion	S: Long Life/Low Noise <b>GN-S</b> Gearhead, RoHS-Compliant <b>RH</b> : Right-Angle/Hollow Shaft Gearhead, RoHS-Compliant	K: GN-K Gearhead RA: Right-Angle/Solid Shaft Gearhead, RoHS-Compliant						
	GE Type Pinion	S: Long Life <b>GE-S</b> Gearhead <b>RH</b> : Right-Angle/Hollow Shaft Gearhead, RoHS-Compliant	RA: Right-Angle/Solid Shaft Gearhead, RoHS-Compliant						

\*GN-K gearhead of frame size 42 mm complies to RoHS directive.

# General Specifications of Motors

#### •1 W, 3 W Type

Item	Specifications
Insulation Resistance	100 M $\Omega$ or more when 500 VDC megger is applied between the windings and the frame after rated motor operation under normal ambient temperature and humidity.
Dielectric Strength	Sufficient to withstand 1.5 kV at 50 Hz or 60 Hz applied between the windings and the frame for 1 minute after rated motor operation under normal ambient temperature and humidity.
Temperature Rise	Temperature rise of windings are 75°C or less measured by the resistance change method after rated motor operation under normal ambient temperature and humidity, with connecting a gearhead or equivalent heat radiation plate*1.
Insulation Class	UL/CSA standards: Class A (105°C), EN standards: Class E (120°C)
Overheat Protection	Impedance protected
Ambient Temperature	$-10^{\circ}$ C $\rightarrow$ +40 $^{\circ}$ C (nonfreezing)
Ambient Humidity	85% or less (noncondensing)
Degree of Protection	IP20

#### ●6 W~90 W Type, 2-Pole, High-Speed Type

Item	Specifications									
Insulation Resistance	100 M $\Omega$ or more when 500 VDC megger is applied between the windings and the frame after rated motor operation under normal ambient temperature and numidity.									
Dielectric Strength	Sufficient to withstand 1.5 kV (three-phase 400 VAC: 2 kV) at 50 Hz and 60 Hz applied between the windings and the frame for 1 minute after rated motor speration under normal ambient temperature and humidity.									
Temperature Rise	iemperature rise of windings are 80°C or less measured by the resistance change method under normal ambient temperature and humidity, after rated motor operation with connecting a gearhead or equivalent heat radiation plate <sup>**1</sup> . (Three-phase type: 70°C or less)									
Insulation Class*2	Class B (130°C)									
Overheat Protection	6 W type has impedance protection. All others have built-in thermal protector (automatic return type) Operating temperature; open: 130°C±5°C, close: 82°C±15°C									
Ambient Temperature	Single-phase 100 VAC, Single-phase 200 VAC, Three-phase 200 VAC: $-10^{\circ}C \sim +50^{\circ}C$ (nonfreezing) Other voltage: $-10^{\circ}C \sim +40^{\circ}C$ (nonfreezing)									
Ambient Humidity	85% or less (noncondensing)									
Degree of Protection	Lead Wire Type:     IP20     IP65 (excluding the installation surface of the round shaft type)       Terminal Box Type:     6 W Type     IP65 (excluding the installation surface of the round shaft type)       25 W, 40 W, 60 W, 90 W Type (Pinion Shaft Type)     IP54       25 W, 40 W, 60 W, 90 W Type (Round Shaft Type)     IP40									

#### \*1 Heat radiation plate (Material: Aluminum)

Motor Type	Size (mm)	Thickness (mm)
1 W, 3 W Type	80×80	
6 W Type	115×115	
15 W Type	125×125	_
25 W Type (2-Pole, High-Speed <b>4IK40</b> Type, <b>4IK60</b> Type)	135×135	
40 W Type (2-Pole, High-Speed <b>5IK60</b> Type)	165×165	
60 W, 90 W, 150 W Type	200×200	

00 10, 3

\*2 The following products are recognized as class E (120°C). 4IK25GN-UT4, 4IK25A-UT4, 5IK40GN-UT4, 5IK40A-UT4, 5IK60GE-UT4F, 5IK60A-UT4F, 5IK90GE-UT4F, 5IK90A-UT4F

1 W / 3 W

# RoHS Induction Motors 1 W / 3 W Frame Size: 42 mm



(Gearhead sold separately)

# Specifications – Continuous Rating (RoHS)

Mode Lead Wire	Output Power	Voltage	Frequency	Current	Starting Torque	Rated Torque	Rated Speed	Capacitor		
Pinion Shaft Type	Round Shaft Type	W	VAC	Hz	Α	mN∙m	mN∙m	r/min	μF	
	01614-4/21	1	Single Phase 100	50	0.107	0	9.5	1000	15	
UKIGN-AWZJ	VIK IA-AWZJ	1	Sillyle-Fildse 100	60	0.102	0	8	1200	1.5	
	01//14-4/4/211	-1	Single-Phase 110	60	0.074	0	0	1000	1.0	
ZP UIKTGIN-AW30	UIK TA-AWSU	1	Single-Phase 115	00	0.078	0	0	1200	1.0	
	0IK1A-CW2J	0.8	Single Dhoos 200	50	0.057	7	0	1000	0.35	
(2P) OIK I GN-CW2J		1	Sillyle-Filase 200	60	0.055	1	0	1200		
TO AIRSON DWOL	OIK3A-BW2J	3	Cingle Dhose 100	50	0.109	6	12	2400	1.0	
ZP UKJGN-BWZJ			Single-Phase 100	60	0.123	0	10	3000	1.0	
TO AIRSON DWOL		2	Single-Phase 110	60	0.115	G	10	2000	1 5	
ZP UK3GN-BW3U	UIKJA-BWJU	3	Single-Phase 115	00	0.118	0	10	3000	1.5	
		2.5	Single Dhoos 200	50	0.057	5	0.5	2500	0.45	
UKSGN-DWZJ	UIKJA-DW2J	3	Sillyle-FildSe 200	60	0.064		9.0	3100		

• The J and U at the end of the model name indicate that the unit includes a capacitor. These letters are not listed on the motor nameplate.

When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

**ZP**: Impedance protected

## Product Line

#### Motor (RoHS)

Tuno	Model								
туре	Pinion Shaft Type	Round Shaft Type							
	0IK1GN-AW2J	OIK1A-AW2J							
	0IK1GN-AW3U	0IK1A-AW3U							
Lood Wire	0IK1GN-CW2J	OIK1A-CW2J							
Leau wire	OIK3GN-BW2J	OIK3A-BW2J							
	OIK3GN-BW3U	OIK3A-BW3U							
	0IK3GN-DW2J	OIK3A-DW2J							

#### Gearhead (Sold Separately) (RoHS)

Туре	Gearhead Model	Gear Ratio
Parallel Shaft	OGN⊡K	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180

• Enter the gear ratio in the box (
) within the model name.

•Gearheads are sold separately. Decimal gearheads are not available.

•Enter the gear ratio in the box  $(\Box)$  within the model name.

A colored background \_\_\_\_\_ indicates gear shaft rotation in the same direction as the motor shaft, while the others rotate in the opposite direction.

The speed is calculated by dividing the motor's synchronous speed (4-pole type; 50 Hz: 1500 r/min, 60 Hz: 1800 r/min, 2-pole type; 50 Hz: 3000 r/min, 60 Hz: 3600 r/min) by the gear ratio. The actual speed is 2 - 33% less than the displayed value, depending on the size of the load.

♦ 50 Hz																				Uni	t = N•m
Model	Speed r/min	500	416	300	250	200	166	120	100	83	60	50	41	30	25	20	16	15	12.5	10	8.3
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
0IK1GN-AW2J	Ó OGN⊡K	0.023	0.028	0.038	0.046	0.058	0.069	0.087	0.1	0.12	0.16	0.19	0.23	0.31	0.38	0.42	0.5	0.56	0.67	0.84	1
0IK1GN-CW2J	/ OGN⊟K	0.019	0.023	0.032	0.039	0.049	0.058	0.073	0.088	0.11	0.13	0.16	0.19	0.26	0.32	0.35	0.42	0.47	0.57	0.71	0.85
Unit = N·m																					
Model	Speed r/min	1000	833	600	500	400	333	240	200	166	120	100	83	60	50	40	33	30	25	20	16
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
OIK3GN-BW2J	/ OGN⊡K	0.029	0.035	0.049	0.058	0.073	0.087	0.11	0.13	0.16	0.2	0.24	0.29	0.4	0.48	0.53	0.64	0.71	0.85	1	1
0IK3GN-DW2J	/ OGN⊡K	0.023	0.028	0.038	0.046	0.058	0.069	0.087	0.1	0.12	0.16	0.19	0.23	0.31	0.38	0.42	0.5	0.56	0.67	0.84	1
<b>⊘60 Hz</b>																				Uni	t = N•m
Model	Speed r/min	600	500	360	300	240	200	144	120	100	72	60	50	36	30	24	20	18	15	12	10
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
0IK1GN-AW2J 0IK1GN-AW3U 0IK1GN-CW2J		0.019	0.023	0.032	0.039	0.049	0.058	0.073	0.088	0.11	0.13	0.16	0.19	0.26	0.32	0.35	0.42	0.47	0.57	0.71	0.85
																				Uni	t = N•m
Model	Speed r/min	1200	1000	720	600	480	400	288	240	200	144	120	100	72	60	48	40	36	30	24	20
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
OIK3GN-BW2J OIK3GN-BW3U	/ OGN⊡K	0.024	0.029	0.041	0.049	0.061	0.073	0.091	0.11	0.13	0.17	0.2	0.24	0.33	0.4	0.44	0.53	0.59	0.71	0.89	1
0IK3GN-DW2J	/ OGN⊡K	0.023	0.028	0.038	0.046	0.058	0.069	0.087	0.1	0.12	0.16	0.19	0.23	0.31	0.38	0.42	0.5	0.56	0.67	0.84	1

M 09

# Permissible Overhung Load and Permissible Thrust Load

Motor (Round shaft type) → Page 107 Gearhead → Page 107

## Permissible Load Inertia J for Gearhead

→ Page 107

#### Dimensions (Unit = mm)

Mounting screws are included with gearheads. 

Mass: Motor 0.3 kg Gearhead 0.2 kg



♦ Shaft Section of Round Shaft Type

The mass and motor's dimensions (excluding the shaft

section) are the same as those of the pinion shaft type.

1 W / 3 W

♦ Capacitor (Included with the motors) ♦ Capacitor Dimensions (mm)



✓ • • • • • • • • • • • • • • • • • • •							
M	odel	Capacitor	Δ	B	C	Mass	Capacitor
Pinion Shaft Type	Round Shaft Type	Model	~		0	(g)	Сар
0IK1GN-AW2J	0IK1A-AW2J	CH15FAUL	31	14.5	23.5	18	
0IK1GN-AW3U	0IK1A-AW3U	CH10FAUL	31	14.5	23.5	18	
0IK1GN-CW2J	OIK1A-CW2J	CH035BFAUL	31	17	27	24	Included
OIK3GN-BW2J	OIK3A-BW2J	CH18FAUL	31	14.5	23.5	18	IIIciuueu
OIK3GN-BW3U	OIK3A-BW3U	CH15FAUL	31	14.5	23.5	18	
0IK3GN-DW2J	0IK3A-DW2J	CH045BFAUL	31	17	27	24	

Connection Diagrams

•The direction of motor rotation is as viewed from the shaft end of the motor. CW represents the clockwise direction, while CCW represents the counterclockwise direction.

Connection diagrams are also valid for the equivalent round shaft type.



PE: Protective Earth

Note:

Change the direction of single-phase motor rotation only after bringing the motor to a stop.

If an attempt is made to change the direction of rotation while the motor is rotating, motor may ignore reversing command or change its direction of rotation after some delay.

# RoHS Induction Motors 6 W Frame Size: 60 mm





(Gearhead sold separately)

# Specifications – Continuous Rating (RoHS)



	Mode Upper Model Name: F Lower Model Name ( ):	Model Name: Pinion Shaft Type Name ( ): Round Shaft Type		Voltage	Frequency	Current	Starting Torque	Rated Torque	Rated Speed	Capacitor
	Lead Wire Type Dimension ①	Terminal Box Type Dimension ②	W	VAC	Hz	А	mN∙m	mN∙m	r/min	μF
	2IK6GN-AW2J	2IK6GN-AW2TJ	6	Single Dhose 100	50	0.199	45	49	1200	25
P	(2IK6A-AW2J)	(2IK6A-AW2TJ)	0	Sillyle-Filase 100	60	0.217	40	41	1450	3.5
	2IK6GN-AW2U	2IK6GN-AW2TU	6	Single-Phase 110	60	0.178	40	41	1450	2.5
P	(2IK6A-AW2U)	(2IK6A-AW2TU)	0	Single-Phase 115	00	0.182	40	41	1450	2.5
	2IK6GN-CW2J	2IK6GN-CW2TJ	6	Single Dhase 200	50	0.100	45	49	1150	0.0
<u>v</u>	(2IK6A-CW2J)	(2IK6A-CW2TJ)	0	Sillyle-Flidse 200	60	0.103	40	41	1450	0.0
				Single Phase 220	50	0.103	38	49	1150	
70	2IK6GN-CW2E	2IK6GN-CW2TE	6	Sillyle-Fildse 220	60	0.091	40	41	1450	0.6
	(2IK6A-CW2E)	(2IK6A-CW2TE)	0	Single Dhase 220	50	0.107	45	49	1200	0.0
				Sillyle-Filase 250	60	0.094	40	41	1450	
				Three Phase 200	50	0.081	49	49	1200	
70	2IK6GN-SW2	2IK6GN-SW2T	6	THEE-FIIdSE 200	60	0.072	41	41	1400	
P	(2IK6A-SW2)	(2IK6A-SW2T)	0	Three-Phase 220	60	0.076	41	41	1500	_
				Three-Phase 230	60	0.079	41	41	1500	

• The J, U and E at the end of the model name indicate that the unit includes a capacitor. These letters are not listed on the motor nameplate. When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

W 09

M 06

2-Pole, High-Speed 40 W $\sim$  150 W

# Product Line Motor (RoHS)

**ZP**: Impedance protected

Turne	Model									
туре	Pinion Shaft Type	Round Shaft Type								
	2IK6GN-AW2J	2IK6A-AW2J								
	2IK6GN-AW2U	2IK6A-AW2U								
Lead Wire	2IK6GN-CW2J	2IK6A-CW2J								
	2IK6GN-CW2E	2IK6A-CW2E								
	2IK6GN-SW2	2IK6A-SW2								
	2IK6GN-AW2TJ	2IK6A-AW2TJ								
	2IK6GN-AW2TU	2IK6A-AW2TU								
Terminal Box	2IK6GN-CW2TJ	2IK6A-CW2TJ								
	2IK6GN-CW2TE	2IK6A-CW2TE								
	2IK6GN-SW2T	2IK6A-SW2T								

#### Gearhead (Sold Separately) (RoHS)

(	·····))	<u> </u>
Туре	Gearhead Model	Gear Ratio
Long Life/Low Noise/ Parallel Shaft	2GN_S	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
	2GN10XS (Decima	al gearhead)

• Enter the gear ratio in the box (
) within the model name.

1 W / 3 W

8 W

15 W

# Induction Motors 2-Pole,

ed Type

Unit = N•m

Gearheads and decimal gearheads are sold separately.

•Enter the code that represents the terminal box type "**T**" in the box (**D**) within the model name.

•Enter the gear ratio in the box  $(\Box)$  within the model name.

A colored background indicates gear shaft rotation in the same direction as the motor shaft, while the others rotate in the opposite direction.

The speed is calculated by dividing the motor's synchronous speed (50 Hz: 1500 r/min, 60 Hz: 1800 r/min) by the gear ratio.

The actual speed is 2 - 20% less than the displayed value, depending on the size of the load.

•To reduce the speed beyond the gear ratio in the table, attach a decimal gearhead (gear ratio: 10) between the gearhead and the motor. In that case, the permissible torque is 3 N·m.

#### **⊘50 Hz**

Model	Speed r/min	500	416	300	250	200	166	120	100	83	60	50	41	30	25	20	16	15	12.5	10	8.3
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
2IK6GN-AW2_J 2IK6GN-CW2_J 2IK6GN-CW2_E 2IK6GN-SW2_	2GN□S	0.12	0.14	0.20	0.24	0.30	0.36	0.50	0.60	0.71	0.89	1.1	1.3	1.6	1.9	2.4	2.9	3	3	3	3
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Model	Speed r/min	600	500	360	300	240	200	144	120	100	72	60	50	36	30	24	20	18	15	12	10
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
2IK6GN-AW2_J 2IK6GN-AW2_U 2IK6GN-CW2_J 2IK6GN-CW2_E 2IK6GN-SW2_	2GN□5	0.10	0.12	0.17	0.20	0.25	0.30	0.42	0.50	0.60	0.75	0.90	1.1	1.4	1.6	2.0	2.4	2.7	3	3	3

# Permissible Overhung Load and Permissible Thrust Load

Motor (Round shaft type) → Page 107 Gearhead → Page 107

# Permissible Load Inertia J for Gearhead

→ Page 107

## Dimensions (Unit = mm)

Mounting screws are included with gearheads.



Detail Drawing of Protective Earth Terminal

Gear Ratio

3~18

25~180

L1

30

40

**Torque Motors** 

Motor Model	Gearhead Model	Gear Ratio	L1
2IK6GN-AW2T		3~18	30
2IK6GN-SW2T	2GN_3	25~180	40

 $\blacksquare$  Specify the type of the capacitor to be included by entering  ${\bf J}, {\bf U}$  or  ${\bf E}$  in the box ( ) within the model name.

70±0.5

Mass

(g)

25

25

20

15

Capacitor

Сар

Included

Enter the gear ratio in the box  $(\Box)$  within the model name.

10±0.5

Lead Wire Type

2IK6GN-AW2J

(2IK6A-AW2J)

2IK6GN-AW2U

(2IK6A-AW2U)

2IK6GN-CW2J

(2IK6A-CW2J)

2IK6GN-CW2E

(2IK6A-CW2E)

Model Upper Model Name: Pinion Shaft Type

Lower Model Name (): Round Shaft Type

Terminal Box Type

2IK6GN-AW2TJ

(2IK6A-AW2TJ)

2IK6GN-AW2TU

(2IK6A-AW2TU)

2IK6GN-CW2TJ

(2IK6A-CW2TJ)

2IK6GN-CW2TE

(2IK6A-CW2TE)

#### $\bullet$ Use cable with a diameter of $\varphi 8 \sim \varphi 12$ mm.

#### $\diamondsuit$ Shaft Section of Round Shaft Type

(Included with single-phase motors)

ĥ

С

The mass and motor's dimensions (excluding the shaft section) are the same as those of the pinion shaft type.



#### ◇Decimal Gearhead Can be connected to GN pinion shaft type. 2GN10XS Mass: 0.2 kg



Capacitor

. Model

CH35FAUL2

CH25FAUL2

CH08BFAUL

CH06BFAUL

A B C

31 17 27

31 17 27

31 17 27

31 14.5 23.5

# •

♦Capacitor

φ4.3

AMP#187

20

40 W

8 W

World K Series

# Induction Motors 2-Pole,

High-Speed Type

# Connection Diagrams

•The direction of motor rotation is as viewed from the shaft end of the motor. CW represents the clockwise direction, while CCW represents the counterclockwise direction.

Connection diagrams are also valid for the equivalent round shaft type.

Specify the type of the capacitor to be included by entering J, U or E in the box (
) within the model name.



PE: Protective Earth

Note:

Change the direction of single-phase motor rotation only after bringing the motor to a stop.

If an attempt is made to change the direction of rotation while the motor is rotating, motor may ignore reversing command or change its direction of rotation after some delay.

# RoHS Induction Motors 15 W Frame Size: 70 mm



(Gearhead sold separately)

# c**Al**us @ CE

# Specifications – Continuous Rating (RoHS)

	Model Lead Wire	Туре	Output Power	Voltage	Frequency	Current	Starting Torque	Rated Torque	Rated Speed	Capacitor
	Pinion Shaft Type	Round Shaft Type	w	VAC	Hz	A	mN∙m	mN∙m	r/min	μF
TD	3IK15GN-AW21	316154-41421	15	Single Phase 100	50	0.36	80	125	1200	5.5
P	JIK I JOIN-AWZJ	JIK I JA-AWZJ	15	Sillyle-Fliase 100	60	0.37	65	105	1450	5.5
	21// 1 5 CNL AW/211	211/154-414/211	15	Single-Phase 110	60	0.33	65	105	1450	4.5
	JIK I JOIN-AWZU	JIK I JA-AWZU	15	Single-Phase 115	00	0.34	00	105	1450	4.0
	21// 15 CN-CW21	21/ 15 4-01/21	15	Single Dhase 200	50	0.18	80	125	1200	1.5
æ	SIK I SOIN-CWZJ	JIK I JA-CWZJ	10	Sillyle-Filase 200	60	0.19	65	105	1450	1.5
				Single Dhase 220	50	0.19	70	125	1200	
			15	Single-Phase 220	60	0.16	65	105	1450	1.0
P	JIK I JUN-CWZE	JIK I JA-CWZE	10	Cingle Dhose 020	50	0.19	75	125	1200	1.0
				Single-Phase 230	60	0.16	65	105	1450	

• The J, U and E at the end of the model name indicate that the unit includes a capacitor. These letters are not listed on the motor nameplate. When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

(D): Contains a built-in thermal protector. If a motor overheats for any reason, the thermal protector is opened and the motor stops.

When the motor temperature drops, the thermal protector closes and the motor restarts. Be sure to turn the motor off before inspecting.

## Product Line

#### Motor (RoHS)

Tuno	Model									
Type	Pinion Shaft Type	Round Shaft Type								
	3IK15GN-AW2J	3IK15A-AW2J								
l and Wira	3IK15GN-AW2U	3IK15A-AW2U								
	3IK15GN-CW2J	3IK15A-CW2J								
	3IK15GN-CW2E	3IK15A-CW2E								

#### Gearhead (Sold Separately) (RoHS)

· · · · · · · · · · · · · · · · · · ·	, <b>,</b> ,	<u> </u>
Туре	Gearhead Model	Gear Ratio
Long Life/Low Noise/ Parallel Shaft	3GN⊡S	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
	3GN10XS (Decima	al gearhead)

• Enter the gear ratio in the box (
) within the model name.

W 09

1 W / 3 W

15 W

•Gearheads and decimal gearheads are sold separately.

•Enter the gear ratio in the box  $(\Box)$  within the model name.

•A colored background indicates gear shaft rotation in the same direction as the motor shaft, while the others rotate in the opposite direction.

The speed is calculated by dividing the motor's synchronous speed (50 Hz: 1500 r/min, 60 Hz: 1800 r/min) by the gear ratio.

The actual speed is 2 - 20% less than the displayed value, depending on the size of the load.

To reduce the speed beyond the gear ratio in the table, attach a decimal gearhead (gear ratio: 10) between the gearhead and the motor. In that case, the permissible torque is 5 N·m.

Model	Speed r/min	500	416	300	250	200	166	120	100	83	60	50	41	30	25	20	16	15	12.5	10	8.3
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
3IK15GN-AW2J 3IK15GN-CW2J 3IK15GN-CW2E	3GN⊡S	0.30	0.36	0.51	0.61	0.76	0.91	1.3	1.5	1.8	2.3	2.7	3.3	4.1	5	5	5	5	5	5	5
<b>⊘60 Hz</b>																				Uni	t = N•m
Model	Speed r/min	600	500	360	300	240	200	144	120	100	72	60	50	36	30	24	20	18	15	12	10
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
3IK15GN-AW2J 3IK15GN-AW2U 3IK15GN-CW2J 3IK15GN-CW2E	3GN□S	0.26	0.31	0.43	0.51	0.64	0.77	1.1	1.3	1.5	1.9	2.3	2.8	3.5	4.2	5	5	5	5	5	5

# Permissible Overhung Load and Permissible Thrust Load

70 4×¢5.5 Thru

ø 5 max

22.5

Motor (Round shaft type) → Page 107 Gearhead → Page 107

## Permissible Load Inertia J for Gearhead

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Motor Leads 300 mm Length

UL Style 3271, AWG20

C

→ Page 107

#### **Dimensions** (Unit = mm)

Mounting screws are included with gearheads.

◇Lead Wire Type

Mass: Motor 1.1 kg Gearhead 0.55 kg

<del>6</del>04

80

Motor Model	Gearhead Model	Gear Ratio	L1
3IK15GN-AW2		3~18	32
3IK15GN-CW2	JGIN_3	25~180	42

• Specify the type of the capacitor to be included by entering J, U or E in the box ([]) within the model name

Enter the gear ratio in the box  $(\Box)$  within the model name.

Protective Earth Terminal M4



Detail Drawing of Protective Earth Terminal

Electromagnetic Brake Motors



2-Pole,

**Reversible Motors** 

ed Type

#### ♦ Shaft Section of Round Shaft Type

The mass and motor's dimensions (excluding the shaft section) are the same as those of the pinion shaft type.



#### ◇Decimal Gearhead Can be connected to GN pinion shaft type. 3GN10XS Mass: 0.3 kg



#### 

(Included with single-phase motors)



|--|

Mo	odel	Capacitor	<u>م</u>	P	C C	Mass	Capacitor			
Pinion Shaft Type	Round Shaft Type	Model		Б		(g)	Сар			
3IK15GN-AW2J	3IK15A-AW2J	CH55FAUL2	38	21	31	40				
3IK15GN-AW2U	3IK15A-AW2U	CH45FAUL2	37	18	27	30	laoludod			
3IK15GN-CW2J	3IK15A-CW2J	CH15BFAUL	38	21	31	35	Included			
3IK15GN-CW2E	3IK15A-CW2E	CH10BFAUL	37	18	27	30				

#### Connection Diagrams

•The direction of motor rotation is as viewed from the shaft end of the motor. CW represents the clockwise direction, while CCW represents the counterclockwise direction.

Connection diagrams are also valid for the equivalent round shaft type.

■Specify the type of the capacitor to be included by entering J, U or E in the box (□) within the model name.



#### PE: Protective Earth

Note:

Change the direction of single-phase motor rotation only after bringing the motor to a stop.

If an attempt is made to change the direction of rotation while the motor is rotating, motor may ignore reversing command or change its direction of rotation after some delay.

W 9

25 W

High-Speed Type

# RoHS Induction Motors 25 W Frame Size: 80 mm



(Gearhead sold separately)

#### Right-angle gearheads (hollow shaft or solid shaft) can be combined. Right-Angle Gearheads → Page 108



# . .

# Specifications – Continuous Rating RoHS

Model Rated Torque Capacitor Upper Model Name: Pinion Shaft Type Output Voltage Frequency Current Starting Torque Rated Lower Model Name (): Round Shaft Type Power Speed Lead Wire Type Terminal Box Type W VAC Hz А mN⋅m mN•m r/min μF Dimension ① Dimension (2) 4IK25GN-AW2J 4IK25GN-AW2TJ 50 0.51 130 205 1200 Single-Phase 100 TP 25 8.0 (4IK25A-AW2J) (4IK25A-AW2TJ) 60 0.52 120 170 1450 4IK25GN-AW2U 4IK25GN-AW2TU Single-Phase 110 TP 25 60 0 46 120 170 1450 65 (4IK25A-AW2U) (4IK25A-AW2TU) Single-Phase 115 4IK25GN-CW2J 4IK25GN-CW2TJ 50 205 1200 TP 25 Single-Phase 200 0.26 120 2.0 (4IK25A-CW2J) (4IK25A-CW2TJ) 60 1450 170 0.27 1200 50 205 Single-Phase 220 110 4IK25GN-CW2E 4IK25GN-CW2TE 60 0.23 170 1450 25 1.5 TP (4IK25A-CW2E) (4IK25A-CW2TE) 205 1200 50 0.27 Single-Phase 230 120 60 0.23 170 1450 0.23 240 50 190 1300 Three-Phase 200 4IK25GN-SW2 4IK25GN-SW2T 60 0.21 160 160 1550 TP 25 (4IK25A-SW2) (4IK25A-SW2T) Three-Phase 220 60 0.21 160 160 1600 Three-Phase 230 60 0.22 160 160 1600 4IK25GN-UT4\* TP 25 Three-Phase 400 50 0.12 240 190 1300 (4IK25A-UT4\*)

• The J, U and E at the end of the model name indicate that the unit includes a capacitor. These letters are not listed on the motor nameplate.

When the motor is approved under various safety standards, the model name on the nameplate is the approved model name. \* Conforms to EN/IEC standards only. Bears the CE Marking.

\* Conforms to EN/IEC standards only Note:

A three-phase 400 VAC motor cannot be used with an inverter. Using them together may lead to deterioration of the motor wiring insulation and damage the products.

(TP): Contains a built-in thermal protector. If a motor overheats for any reason, the thermal protector is opened and the motor stops.

When the motor temperature drops, the thermal protector closes and the motor restarts. Be sure to turn the motor off before inspecting.

# Product Line

#### Motor Rolls

Tupo	Ma	del
туре	Pinion Shaft Type	Round Shaft Type
	4IK25GN-AW2J	4IK25A-AW2J
	4IK25GN-AW2U	4IK25A-AW2U
Lead Wire	4IK25GN-CW2J	4IK25A-CW2J
	4IK25GN-CW2E	4IK25A-CW2E
	4IK25GN-SW2	4IK25A-SW2
	4IK25GN-AW2TJ	4IK25A-AW2TJ
	4IK25GN-AW2TU	4IK25A-AW2TU
Torminal Poy	4IK25GN-CW2TJ	4IK25A-CW2TJ
Terminal Box	4IK25GN-CW2TE	4IK25A-CW2TE
	4IK25GN-SW2T	4IK25A-SW2T
	4IK25GN-UT4	4IK25A-UT4

#### Gearhead/Right-Angle Gearhead (Sold Separately) (Rolls)

Туре	Gearhead Model	Gear Ratio						
Long Life/Low Noise/ Parallel Shaft	4GN⊡S	3, 3.6, 5, 6, 7.5, 9, 12.5, 15 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180						
	4GN10XS (Decimal gearhead)							
Right-Angle/ Hollow Shaft	4GN⊡RH	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180						
Right-Angle/ Solid Shaft	4GN RA	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180						

• Enter the gear ratio in the box  $(\Box)$  within the model name.

Gearheads and decimal gearheads are sold separately.

●Enter the code that represents the terminal box type "T" in the box (□) within the model name.

•Enter the gear ratio in the box  $(\Box)$  within the model name.

A colored background indicates gear shaft rotation in the same direction as the motor shaft, while the others rotate in the opposite direction.

•The speed is calculated by dividing the motor's synchronous speed (50 Hz: 1500 r/min, 60 Hz: 1800 r/min) by the gear ratio.

The actual speed is 2 - 20% less than the displayed value, depending on the size of the load.

To reduce the speed beyond the gear ratio in the table, attach a decimal gearhead (gear ratio: 10) between the gearhead and the motor. In that case, the permissible torque is 8 N·m. When a gearhead of 1/25~1/36 is connected, the value for permissible torque is 6 N·m.

<b>⊘50 Hz</b>																				Unit	t = N•m
Model	Speed r/min	500	416	300	250	200	166	120	100	83	60	50	41	30	25	20	16	15	12.5	10	8.3
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
4IK25GN-AW2_J 4IK25GN-CW2_J 4IK25GN-CW2_E	dGN⊡S	0.50	0.60	0.83	1.0	1.2	1.5	2.1	2.5	3.0	3.7	4.5	5.4	6.8	8	8	8	8	8	8	8
4IK25GN-SW2 4IK25GN-UT4	∕ 4GN⊡S	0.46	0.55	0.77	0.92	1.2	1.4	1.9	2.3	2.8	3.5	4.2	5.0	6.3	7.5	8	8	8	8	8	8
																				Uni	t = N•m

#### 

/00112																				Unit	- 14 111
Model	Speed r/min	600	500	360	300	240	200	144	120	100	72	60	50	36	30	24	20	18	15	12	10
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
4IK25GN-AW2 <b>_</b> J 4IK25GN-AW2 <b>_</b> U 4IK25GN-CW2 <b>_</b> J 4IK25GN-CW2 <b>_</b> E	dgn⊡s	0.41	0.50	0.69	0.83	1.0	1.2	1.7	2.1	2.5	3.1	3.7	4.5	5.6	6.7	8	8	8	8	8	8
4IK25GN-SW2	/ 4GN□S	0.39	0.47	0.65	0.78	0.97	1.2	1.6	1.9	2.3	2.9	3.5	4.2	5.3	6.3	7.9	8	8	8	8	8

40 W

World K Series

1 W / 3 W

**M 9** 

15 W

## Permissible Overhung Load and Permissible Thrust Load

Motor (Round shaft type) → Page 107 Gearhead → Page 107

## Permissible Load Inertia J for Gearhead

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Motor Leads 300 mm Length

UL Style 3271, AWG20

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22.5

5 max

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→ Page 107

♦ Lead Wire Type ① Mass: Motor 1.5 kg

Gearhead 0.65 kg

85

#### Dimensions (Unit = mm)

Mounting screws are included with gearheads.

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Detail Drawing of Protective Earth Terminal

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Right-Angle Gearheads

Brake Pack SB50W

Accessories



• Use cable with a diameter of  $\phi 6 \sim \phi 12$  mm.

♦Capacitor

φ4.3

AMP#187

20

#### ♦ Shaft Section of Round Shaft Type

(Included with single-phase motors)

9

The mass and motor's dimensions (excluding the shaft section) are the same as those of the pinion shaft type.



∧ Capacitor Dimonsions (mm)

	Mc Upper Model Name Lower Model Name	Capacitor Model	A	В	С	Mass (g)	Capacitor Cap				
	Lead Wire Type	Terminal Box Type									
	4IK25GN-AW2J (4IK25A-AW2J)	4IK25GN-AW2TJ (4IK25A-AW2TJ)	CH80CFAUL2	48	21	31	45				
	4IK25GN-AW2U (4IK25A-AW2U)	4IK25GN-AW2TU (4IK25A-AW2TU)	CH65CFAUL2	48	19	29	40	Included			
	4IK25GN-CW2J (4IK25A-CW2J)	4IK25GN-CW2TJ (4IK25A-CW2TJ)	CH20BFAUL	48	19	29	35	Included			
_	4IK25GN-CW2E (4IK25A-CW2E)	4IK25GN-CW2TE (4IK25A-CW2TE)	CH15BFAUL	38	21	31	35				

Motor Model	Gearhead Model	Gear Ratio	L1
4IK25GN-AW2T 4IK25GN-CW2T		3~18	32
4IK25GN-SW2T 4IK25GN-UT4	40N_3	25~180	42.5

• Specify the type of the capacitor to be included by entering J, U or E in the box (

Enter the gear ratio in the box  $(\Box)$  within the model name.

(The key is included with the gearhead)



0.040 -0-1 ŝ



Can be connected to GN pinion shaft type. 4GN10XS

Mass: 0.4 kg

32





# Connection Diagrams

•The direction of motor rotation is as viewed from the shaft end of the motor. CW represents the clockwise direction, while CCW represents the counterclockwise direction.

Connection diagrams are also valid for the equivalent round shaft type.

●Specify the type of the capacitor to be included by entering J, U or E in the box (□) within the model name.

Lead W	ire Type	Terminal Box Type							
4IK25GN-AW2□ 4IK25GN-CW2□	4IK25GN-SW2	4IK25GN-AW2T⊟ 4IK25GN-CW2T⊡	4IK25GN-SW2T 4IK25GN-UT4						
Clockwise	Clockwise L1(R) L2(S) L3(T) Black CW CW CW CW PE	Clockwise	Clockwise L1(R) L2(S) L3(T) PE						
Counterclockwise	<b>Counterclockwise</b> To change the rotation direction, change any two connections between R, S and T.	Counterclockwise	<b>Counterclockwise</b> To change the rotation direction, change any two connections between U, V and W.						
No Black PE		Lo 22 No UI Capacitor PE							

PE: Protective Earth

Note:

Change the direction of single-phase motor rotation only after bringing the motor to a stop.

If an attempt is made to change the direction of rotation while the motor is rotating, motor may ignore reversing command or change its direction of rotation after some delay.

15 W

World K Series

1 W / 3 W

High-Sp

eed Type

# RoHS Induction Motors 40 W Frame Size: 90 mm

Lead Wire Type (Gearhead sold separately)

Right-angle gearheads (hollow shaft or solid shaft) can be combined. Right-Angle Gearheads → Page 108



# Specifications – Continuous Rating (RoHS)

	Model Upper Model Name: Pinion Shaft Type Lower Model Name ( ): Round Shaft Type		Output Power	Voltage	Frequency	Current	Starting Torque	Rated Torque	Rated Speed	Capacitor	
	Lead Wire Type Dimension ①	Terminal Box Type Dimension ②	W	VAC	Hz	A	mN∙m	mN∙m	r/min	μF	
	5IK40GN-AW2J	5IK40GN-AW2TJ	40	Single Dhose 100	50	0.76	200	315	1250	11	
P	(5IK40A-AW2J)	(5IK40A-AW2TJ)	40	Single-Phase 100	60	0.74	200	260	1500		
	5IK40GN-AW2U	40GN-AW2U 5IK40GN-AW2TU (40A-AW2U) (5IK40A-AW2TU)		Single-Phase 110	60	0.68	200	260	1500	0.0	
P	(5IK40A-AW2U)			Single-Phase 115	0.67		200	200	1500	9.0	
	5IK40GN-CW2J	5IK40GN-CW2TJ	40	Cingle Dhees 200	50	0.39	200	315	1250	2.0	
P	(5IK40A-CW2J)	(5IK40A-CW2TJ)	40	Single-1 hase 200	60	0.40	200	260	1500	3.0	
			40	Cingle Dhees 200	50	0.39		315	1250	2.3	
	5IK40GN-CW2E	5IK40GN-CW2TE (5IK40A-CW2TE)		Sillyle-Flidse 220	60	0.35	200	260	1500		
P	(5IK40A-CW2E)			Cingle Dhees 220	50	0.39	200	300	1300		
				Single-Phase 230	60	0.34		260	1500		
				Three Dhees 200	50	0.32	400	300	1300		
	5IK40GN-SW2	5IK40GN-SW2T	40	Three-Phase 200	60	0.30	260	260	1550		
P	(5IK40A-SW2)	(5IK40A-SW2T)	40	Three-Phase 220	60	0.30	260	260	1600	_	
	ν · / γ			Three-Phase 230	60	0.31	260	260	1600		
TP	_	5IK40GN-UT4* (5IK40A-UT4*)	40	Three-Phase 400	50	0.16	500	315	1250	_	

• The J, U and E at the end of the model name indicate that the unit includes a capacitor. These letters are not listed on the motor nameplate.

When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

\* Conforms to EN/IEC standards only. Bears the CE Marking.

Note:

A three-phase 400 VAC motor cannot be used with an inverter. Using them together may lead to deterioration of the motor wiring insulation and damage the products.

(D): Contains a built-in thermal protector. If a motor overheats for any reason, the thermal protector is opened and the motor stops.

When the motor temperature drops, the thermal protector closes and the motor restarts. Be sure to turn the motor off before inspecting.

# Product Line

#### Motor Rolls

Tuno	Mo	del
туре	Pinion Shaft Type	Round Shaft Type
	5IK40GN-AW2J	5IK40A-AW2J
	5IK40GN-AW2U	5IK40A-AW2U
Lead Wire	5IK40GN-CW2J	5IK40A-CW2J
	5IK40GN-CW2E	5IK40A-CW2E
	5IK40GN-SW2	5IK40A-SW2
	5IK40GN-AW2TJ	5IK40A-AW2TJ
	5IK40GN-AW2TU	5IK40A-AW2TU
Torminal Poy	5IK40GN-CW2TJ	5IK40A-CW2TJ
Terminal Box	5IK40GN-CW2TE	5IK40A-CW2TE
	5IK40GN-SW2T	5IK40A-SW2T
	5IK40GN-UT4	5IK40A-UT4

#### • Gearhead/Right-Angle Gearhead (Sold Separately) (RoHS)

Туре	Gearhead Model	Gear Ratio
Long Life/Low Noise/ Parallel Shaft	5GN□S	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
	5GN10XS (Decima	al gearhead)
Right-Angle/ Hollow Shaft	5GN□RH	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
Right-Angle/ Solid Shaft	5GN <b></b> RA	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180

• Enter the gear ratio in the box (
) within the model name.

25

•Gearheads and decimal gearheads are sold separately.

●Enter the code that represents the terminal box type "T" in the box (□) within the model name.

•Enter the gear ratio in the box ( $\Box$ ) within the model name.

•A colored background indicates gear shaft rotation in the same direction as the motor shaft, while the others rotate in the opposite direction.

The speed is calculated by dividing the motor's synchronous speed (50 Hz: 1500 r/min, 60 Hz: 1800 r/min) by the gear ratio.

The actual speed is 2 - 20% less than the displayed value, depending on the size of the load.

•To reduce the speed beyond the gear ratio in the table, attach a decimal gearhead (gear ratio: 10) between the gearhead and the motor. In that case, the permissible torque is 10 N·m.

																				Uni	i = N m
Model	Speed r/min	500	416	300	250	200	166	120	100	83	60	50	41	30	25	20	16	15	12.5	10	8.3
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
5IK40GN-AW2_J 5IK40GN-CW2_J 5IK40GN-CW2_E (Single-phase 220 VAC)	5GN⊡S	0.77	0.92	1.3	1.5	1.9	2.3	3.2	3.8	4.6	5.7	6.9	8.3	10	10	10	10	10	10	10	10
5IK40GN-CW2E (Single-phase 230 VAC) 5IK40GN-SW2/	∕ 5GN⊡S	0.73	0.87	1.2	1.5	1.8	2.2	3.0	3.6	4.4	5.5	6.6	7.9	9.9	10	10	10	10	10	10	10
5IK40GN-UT4	/ 5GN□S	0.77	0.92	1.3	1.5	1.9	2.3	3.2	3.8	4.6	5.7	6.9	8.3	10	10	10	10	10	10	10	10
<b>◇60 Hz</b>																				Unit	t = N•m
Model	Speed	600	500	360	300	240	200	144	120	100	72	60	50	36	30	24	20	18	15	12	10

Model	Speed r/min	600	500	360	300	240	200	144	120	100	72	60	50	36	30	24	20	18	15	12	10
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
5IK40GN-AW2_J 5IK40GN-AW2_U 5IK40GN-CW2_J 5IK40GN-CW2_E 5IK40GN-SW2_	5GN□S	0.63	0.76	1.1	1.3	1.6	1.9	2.6	3.2	3.8	4.7	5.7	6.8	8.6	10	10	10	10	10	10	10

## Permissible Overhung Load and Permissible Thrust Load

Motor (Round shaft type) → Page 107 Gearhead → Page 107

## Permissible Load Inertia J for Gearhead

→ Page 107

#### Dimensions (Unit = mm)

Mounting screws are included with gearheads.

◇Lead Wire Type ① Mass: Motor 2.5 kg Gearhead 1.5 kg

Motor Model	Gearhead Model	Gear Ratio	L1
5IK40GN-AW2	ECNITC	3~18	42
5IK40GN-CW2	JGN_J	25~180	60

 $\blacksquare$  Specify the type of the capacitor to be included by entering  ${\bf J}, {\bf U}$  or  ${\bf E}$  in the box ()) within the model name.

Enter the gear ratio in the box ( $\Box$ ) within the model name.



1 W / 3 W

^ .....

15 W

Motor Model	Gearhead Model	Gear Ratio	L1	
5IK40GN-AW2T 5IK40GN-CW2T 5IK40GN-SW2T 5IK40GN-UT4	5GN S	3~18	42	
	SGN_5	25~180	60	

 $\bullet$  Specify the type of the capacitor to be included by entering  ${\bf J}, {\bf U}$  or  ${\bf E}$  in the box ([]) within the model name

Enter the gear ratio in the box  $(\Box)$  within the model name.



(The key is included with the gearhead)



 $\bullet$  Use cable with a diameter of  $\varphi 6 \sim \varphi 12$  mm.

#### $\diamondsuit$ Shaft Section of Round Shaft Type

The mass and motor's dimensions (excluding the shaft section) are the same as those of the pinion shaft type.



♦ Decimal Gearhead Can be connected to **GN** pinion shaft type. 5GN10XS Mass: 0.6 kg



(Included with single-phase motors)



	Dimensions	(mm)
--	------------	------

Mc Upper Model Name Lower Model Name	Capacitor Model	A	В	С	Mass (g)	Capacitor Cap	
Lead Wire Type	Terminal Box Type						
5IK40GN-AW2J (5IK40A-AW2J)	5IK40GN-AW2TJ (5IK40A-AW2TJ)	CH110CFAUL2	58	21	31	50	
5IK40GN-AW2U (5IK40A-AW2U)	5IK40GN-AW2TU (5IK40A-AW2TU)	CH90CFAUL2	48	22.5	31.5	45	Included
5IK40GN-CW2J (5IK40A-CW2J)	5IK40GN-CW2TJ (5IK40A-CW2TJ)	CH30BFAUL	58	21	31	50	Included
5IK40GN-CW2E (5IK40A-CW2E)	5IK40GN-CW2TE (5IK40A-CW2TE)	CH23BFAUL	48	21	31	40	

# Connection Diagrams

•The direction of motor rotation is as viewed from the shaft end of the motor. CW represents the clockwise direction, while CCW represents the counterclockwise direction.

•Connection diagrams are also valid for the equivalent round shaft type.

●Specify the type of the capacitor to be included by entering J, U or E in the box (□) within the model name.

	, ,	\/									
Lead W	ire Type	Terminal Box Type									
5IK40GN-AW2 5IK40GN-CW2	5IK40GN-SW2	5IK40GN-AW2T□ 5IK40GN-CW2T□	5IK40GN-SW2T 5IK40GN-UT4								
Clockwise		Clockwise									
Lo	L2(S) White Motor L3(T) Black Motor	Longracitor PE	L2(S) L3(T) PE								
	Counterclockwise		Counterclockwise								
	To change the rotation direction		To change the rotation direction								
Counterclockwise	change any two connections between R, S and T.	Counterclockwise	change any two connections between U, V and W.								
Low White Red Now Black Motor Capacitor		Lo No Capacitor PE									

PE: Protective Earth

Note:

Change the direction of single-phase motor rotation only after bringing the motor to a stop.

If an attempt is made to change the direction of rotation while the motor is rotating, motor may ignore reversing command or change its direction of rotation after some delay.

World K Series

1 W / 3 W

W 9

High-Speed Type

# Right-Angle Gearheads

# RoHS Induction Motors 60 W Frame Size: 90 mm





(Gearhead sold separately)

# Specifications – Continuous Rating (RoHS)

Model Output Starting Torque Rated Torque Voltage Frequency Current Rated Capacitor Upper Model Name: Pinion Shaft Type Lower Model Name (): Round Shaft Type Power Speed Lead Wire Type Terminal Box Type W VAC Hz А mN∙m mN∙m r/min μF Dimension (1) Dimension (2) 5IK60GE-AW2J 5IK60GE-AW2TJ 50 1.20 490 1200 TP Single-Phase 100 60 320 20 (5IK60A-AW2J) (5IK60A-AW2TJ) 60 1.19 405 1450 5IK60GE-AW2U 5IK60GE-AW2TU Single-Phase 110 1.09 405 TP 60 60 320 1450 18 (5IK60A-AW2U) (5IK60A-AW2TU) Single-Phase 115 1.10 5IK60GE-CW2J 5IK60GE-CW2TJ 50 0.57 490 1200 Single-Phase 200 TP 60 320 5.0 (5IK60A-CW2J) (5IK60A-CW2TJ) 60 0.65 405 1450 0.55 490 1200 50 Single-Phase 220 0.54 5IK60GE-CW2E 5IK60GE-CW2TE 60 405 1450 TP 60 320 4.0 (5IK60A-CW2E) (5IK60A-CW2TE) 490 50 0.57 1200 Single-Phase 230 0 54 405 1450 60 50 0.50 600 450 1300 Three-Phase 200 5IK60GE-SW2 5IK60GE-SW2T 60 0.43 500 380 1550 TP 60 (5IK60A-SW2) (5IK60A-SW2T) Three-Phase 220 60 0.45 500 380 1600 Three-Phase 230 60 0.46 500 380 1600 5IK60GE-UT4F TP 60 Three-Phase 400 50 0.25 550 470 1250 (5IK60A-UT4F\*)

• The J, U and E at the end of the model name indicate that the unit includes a capacitor. These letters are not listed on the motor nameplate.

When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

\* Conforms to EN/IEC standards only. Bears the CE Marking.

#### Note:

A three-phase 400 VAC motor cannot be used with an inverter. Using them together may lead to deterioration of the motor wiring insulation and damage the products.

(D): Contains a built-in thermal protector. If a motor overheats for any reason, the thermal protector is opened and the motor stops

When the motor temperature drops, the thermal protector closes and the motor restarts. Be sure to turn the motor off before inspecting.

# Product Line

#### Motor (RoHS)

Tuno	Model								
туре	Pinion Shaft Type	Round Shaft Type							
	5IK60GE-AW2J	5IK60A-AW2J							
	5IK60GE-AW2U	5IK60A-AW2U							
Lead Wire	5IK60GE-CW2J	5IK60A-CW2J							
	5IK60GE-CW2E	5IK60A-CW2E							
	5IK60GE-SW2	5IK60A-SW2							
	5IK60GE-AW2TJ	5IK60A-AW2TJ							
	5IK60GE-AW2TU	5IK60A-AW2TU							
Torminal Poy	5IK60GE-CW2TJ	5IK60A-CW2TJ							
Terrinidi Dux	5IK60GE-CW2TE	5IK60A-CW2TE							
	5IK60GE-SW2T	5IK60A-SW2T							
	5IK60GE-UT4F	5IK60A-UT4F							

#### Gearhead/Right-Angle Gearhead (Sold Separately) (RoHS)

Right-angle gearheads (hollow shaft or solid shaft)

Right-Angle Gearheads → Page 108

can be combined.

Туре	Gearhead Model	Gear Ratio
Long Life/ Parallel Shaft	5GE⊡S	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
	5GE10XS (Decima	l gearhead)
Right-Angle/ Hollow Shaft	5GE⊡RH	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
Right-Angle/ Solid Shaft	5GE_RA	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180

• Enter the gear ratio in the box (
) within the model name.

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Gearheads and decimal gearheads are sold separately.

●Enter the code that represents the terminal box type "T" in the box (□) within the model name.

•Enter the gear ratio in the box  $(\Box)$  within the model name.

A colored background indicates gear shaft rotation in the same direction as the motor shaft, while the others rotate in the opposite direction.

•The speed is calculated by dividing the motor's synchronous speed (50 Hz: 1500 r/min, 60 Hz: 1800 r/min) by the gear ratio.

The actual speed is 2 - 20% less than the displayed value, depending on the size of the load.

To reduce the speed beyond the gear ratio in the table, attach a decimal gearhead (gear ratio: 10) between the gearhead and the motor. In that case, the permissible torque is 20 N·m.

20 20 20 20 20

<b>⊘50 Hz</b>																				Uni	t = N∙m
Model	Speed r/min	500	416	300	250	200	166	120	100	83	60	50	41	30	25	20	16	15	12.5	10	8.3
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
5IK60GE-AW2_J 5IK60GE-CW2_J 5IK60GE-CW2_E	5GE_S	1.2	1.4	2.0	2.4	3.0	3.6	4.5	5.4	6.4	8.1	9.7	11.6	16.2	19.4	20	20	20	20	20	20
5IK60GE-SW2	∕ 5GE⊡S	1.1	1.3	1.8	2.2	2.7	3.3	4.1	4.9	5.9	7.4	8.9	10.7	14.9	17.8	19.9	20	20	20	20	20
5IK60GE-UT4F	∕ 5GE⊡S	1.1	1.4	1.9	2.3	2.9	3.4	4.3	5.1	6.2	7.8	9.3	11	16	19	20	20	20	20	20	20
<b>⊘60 Hz</b>																				Uni	t = N•m
Model	Speed r/min	600	500	360	300	240	200	144	120	100	72	60	50	36	30	24	20	18	15	12	10
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
5IK60GE-AW2_J 5IK60GE-AW2_U 5IK60GE-CW2_J	5GE□S	0.98	1.2	1.6	2.0	2.5	3.0	3.7	4.4	5.3	6.7	8.0	9.6	13.4	16.0	17.9	20	20	20	20	20

1.5 1.8 2.3 2.8 3.5 4.2 5.0 6.3 7.5 9.0 12.5 15.0 16.8

# Permissible Overhung Load and Permissible Thrust Load

0.92 1.1

Motor (Round shaft type) → Page 107 Gearhead → Page 107

# Permissible Load Inertia J for Gearhead

5GE S

→ Page 107

5IK60GE-CW2 5IK60GE-SW2

#### Dimensions (Unit = mm)

Mounting screws are included with gearheads.

#### ♦ Lead Wire Type ①

Mass: Motor 2.7 kg Gearhead 1.5 kg



15 W

World K Series

1W/3W

8 ₩

40 W

00 W

 $40 W \sim 150 W$ 

Orerminal Box Type ②
 Mass: Motor 2.8 kg
 Gearhead 1.5 kg



 $\bullet$  Use cable with a diameter of  $\varphi 6 \sim \varphi 12$  mm.

#### $\diamondsuit$ Shaft Section of Round Shaft Type

The mass and motor's dimensions (excluding the shaft section) are the same as those of the pinion shaft type.



♦ Decimal Gearhead

Can be connected to **GE** pinion shaft type. **5GE10XS** 

Mass: 0.6 kg



(Included with single-phase motors)



#### 

Mo Upper Model Name Lower Model Name	odel e: Pinion Shaft Type ( ): Round Shaft Type	Capacitor Model	A	В	С	Mass (g)	Capacitor Cap
Lead Wire Type	Terminal Box Type						
5IK60GE-AW2J (5IK60A-AW2J)	5IK60GE-AW2TJ (5IK60A-AW2TJ)	CH200CFAUL2	58	29	41	95	
5IK60GE-AW2U (5IK60A-AW2U)	5IK60GE-AW2TU (5IK60A-AW2TU)	CH180CFAUL2	58	29	41	95	la chude d
5IK60GE-CW2J (5IK60A-CW2J)	5IK60GE-CW2TJ (5IK60A-CW2TJ)	CH50BFAUL	58	29	41	85	inciuded
5IK60GE-CW2E (5IK60A-CW2E)	5IK60GE-CW2TE (5IK60A-CW2TE)	CH40BFAUL	58	23.5	37	70	

Brake Pack SB50W

# Connection Diagrams

•The direction of motor rotation is as viewed from the shaft end of the motor. CW represents the clockwise direction, while CCW represents the counterclockwise direction.

•Connection diagrams are also valid for the equivalent round shaft type.

●Specify the type of the capacitor to be included by entering J, U or E in the box (□) within the model name.

	, 0,	()								
Lead W	/ire Type	Terminal Box Type								
5IK60GE-AW2 5IK60GE-CW2	5IK60GE-SW2	5IK60GE-AW2T 5IK60GE-CW2T	5IK60GE-SW2T 5IK60GE-UT4F							
Clockwise White Comparison Notor Comparison Compa	Clockwise	Clockwise	Clockwise							
Counterclockwise	<b>Counterclockwise</b> To change the rotation direction, change any two connections between R, S and T.	Counterclockwise	<b>Counterclockwise</b> To change the rotation direction, change any two connections between U, V and W.							
Low White Red Now Black Motor Capacitor		Lo Z2 No U1 Capacitor PE								

PE: Protective Earth

#### Note:

Change the direction of single-phase motor rotation only after bringing the motor to a stop.

If an attempt is made to change the direction of rotation while the motor is rotating, motor may ignore reversing command or change its direction of rotation after some delay.

High-Sp

ed Type

# Right-Angle Gearheads

# RoHS Induction Motors 90 W Frame Size: 90 mm



Right-angle gearheads (hollow shaft or solid shaft) can be combined. Right-Angle Gearheads → Page 108





# Specifications – Continuous Rating Rolls

Model Output Voltage Frequency Starting Torque Rated Torque Rated Capacitor Upper Model Name: Pinion Shaft Type Current Speed Lower Model Name (): Round Shaft Type Power Lead Wire Type Terminal Box Type W VAC Hz mN∙m mN∙m А r/min μF Dimension (1) Dimension (2) 5IK90GE-AW2J 5IK60GE-AW2TJ 50 1.64 700 1250 Single-Phase 100 450 28 TP 90 (5IK90A-AW2J) (5IK90A-AW2TJ) 60 1.67 585 1500 5IK90GE-AW2U 5IK90GE-AW2TU 1.45 Single-Phase 110 TP 90 60 450 585 1500 20 (5IK90A-AW2U) (5IK90A-AW2TU) Single-Phase 115 1.44 730 50 0.80 1200 5IK90GE-CW2TJ 5IK90GE-CW2J TP 90 Single-Phase 200 450 7.0 (5IK90A-CW2J) (5IK90A-CW2TJ) 60 0.93 605 1450 0.74 730 1200 50 Single-Phase 220 5IK90GE-CW2E 5IK90GE-CW2TE 0.82 605 1450 60 TP 90 450 60 (5IK90A-CW2E) (5IK90A-CW2TE) 0.76 730 1200 50 Single-Phase 230 60 0.81 605 1450 850 680 1300 50 0 64 Three-Phase 200 5IK90GE-SW2 5IK90GE-SW2T 60 0.59 700 570 1550 TP 90 (5IK90A-SW2) (5IK90A-SW2T) Three-Phase 220 60 0.60 700 570 1600 Three-Phase 230 0.61 700 570 1600 60 5IK90GE-UT4F TP Three-Phase 400 850 700 1250 90 50 0.35 \_ (5IK90A-UT4F\*)

• The J, U and E at the end of the model name indicate that the unit includes a capacitor. These letters are not listed on the motor nameplate.

When the motor is approved under various safety standards, the model name on the nameplate is the approved model name \* Conforms to EN/IEC standards only. Bears the CE Marking.

Note

A three-phase 400 VAC motor cannot be used with an inverter. Using them together may lead to deterioration of the motor wiring insulation and damage the products.

(D): Contains a built-in thermal protector. If a motor overheats for any reason, the thermal protector is opened and the motor stops.

When the motor temperature drops, the thermal protector closes and the motor restarts. Be sure to turn the motor off before inspecting,

# Product Line

#### Motor (RoHS)

Tupo	Model									
туре	Pinion Shaft Type	Round Shaft Type								
	5IK90GE-AW2J	5IK90A-AW2J								
Lead Wire	5IK90GE-AW2U	5IK90A-AW2U								
	5IK90GE-CW2J	5IK90A-CW2J								
	5IK90GE-CW2E	5IK90A-CW2E								
	5IK90GE-SW2	5IK90A-SW2								
	5IK90GE-AW2TJ	5IK90A-AW2TJ								
	5IK90GE-AW2TU	5IK90A-AW2TU								
Torminal Poy	5IK90GE-CW2TJ	5IK90A-CW2TJ								
Terminal Box	5IK90GE-CW2TE	5IK90A-CW2TE								
	5IK90GE-SW2T	5IK90A-SW2T								
	5IK90GE-UT4F	5IK90A-UT4F								

#### • Gearhead/Right-Angle Gearhead (Sold Separately) (RoHS)

Туре	Gearhead Model	Gear Ratio
Long Life/ Parallel Shaft	5GE <sup></sup> S	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
	5GE10XS (Decima	l gearhead)
Right-Angle/ Hollow Shaft	5GE_RH	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
Right-Angle/ Solid Shaft	5GE□RA	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180

• Enter the gear ratio in the box (
) within the model name

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Gearheads and decimal gearheads are sold separately.

•Enter the code that represents the terminal box type "T" in the box (
) within the model name.

•Enter the gear ratio in the box  $(\Box)$  within the model name.

A colored background indicates gear shaft rotation in the same direction as the motor shaft, while the others rotate in the opposite direction.

•The speed is calculated by dividing the motor's synchronous speed (50 Hz: 1500 r/min, 60 Hz: 1800 r/min) by the gear ratio.

The actual speed is 2 - 20% less than the displayed value, depending on the size of the load.

To reduce the speed beyond the gear ratio in the table, attach a decimal gearhead (gear ratio: 10) between the gearhead and the motor. In that case, the permissible torque is 20 N·m.

Unit = N•m

#### ♦ 50 Hz

Model	Speed r/min	500	416	300	250	200	166	120	100	83	60	50	41	30	25	20	16	15	12.5	10	8.3
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
5IK90GE-AW2_J	/ 5GE⊡S	1.7	2.0	2.8	3.4	4.3	5.1	6.4	7.7	9.2	11.6	13.9	16.6	20	20	20	20	20	20	20	20
5IK90GE-CW2_J 5IK90GE-CW2_E	∕ 5GE⊡S	1.8	2.1	3.0	3.5	4.4	5.3	6.7	8.0	9.6	12.0	14.5	17.3	20	20	20	20	20	20	20	20
5IK90GE-SW2	∕ 5GE⊡S	1.7	2.0	2.8	3.3	4.1	5.0	6.2	7.4	8.9	11.2	13.5	16.2	20	20	20	20	20	20	20	20
5IK90GE-UT4F	∕ 5GE⊡S	1.7	2.0	2.8	3.4	4.3	5.1	6.4	7.7	9.2	12	14	17	20	20	20	20	20	20	20	20
<b>◇60 Hz</b>																				Uni	t = N•m

#### **⊘60 Hz**

Model	Speed r/min	600	500	360	300	240	200	144	120	100	72	60	50	36	30	24	20	18	15	12	10
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
5IK90GE-AW2J 5IK90GE-AW2U	∕ 5GE⊡S	1.4	1.7	2.4	2.8	3.6	4.3	5.3	6.4	7.7	9.7	11.6	13.9	19.3	20	20	20	20	20	20	20
5IK90GE-CW2UJ 5IK90GE-CW2UE	∕ 5GE⊡S	1.5	1.8	2.5	2.9	3.7	4.4	5.5	6.6	7.9	10.0	12.0	14.4	20	20	20	20	20	20	20	20
5IK90GE-SW2	/ 5GE S	1.4	1.7	2.3	2.8	3.5	4.2	5.2	62	7.5	94	11.3	13.5	18.8	20	20	20	20	20	20	20

40 W

# Permissible Overhung Load and Permissible Thrust Load

Motor (Round shaft type) → Page 107 Gearhead → Page 107

# Permissible Load Inertia J for Gearhead

→ Page 107

#### Dimensions (Unit = mm)

Mounting screws are included with gearheads.

 $\diamond$ Lead Wire Type (1) Mass: Motor 3.2 kg

Gearhead 1.5 kg



1W/3W

8 ₩

15 W

Cerrinal Box Type (2) Mass: Motor 3.3 kg Gearhead 1.5 kg



• Use cable with a diameter of  $\phi 6 \sim \phi 12$  mm.

#### $\diamondsuit \mathsf{Shaft}$ Section of Round Shaft Type

The mass and motor's dimensions (excluding the shaft section) are the same as those of the pinion shaft type.



◇Decimal Gearhead Can be connected to GE pinion shaft type. 5GE10XS Mass: 0.6 kg







#### $\diamondsuit$ Capacitor Dimensions (mm)

Mo Upper Model Name Lower Model Name	Capacitor Model	A	В	С	Mass (g)	Capacitor Cap	
Lead Wire Type	Terminal Box Type						
5IK90GE-AW2J (5IK90A-AW2J)	5IK90GE-AW2TJ (5IK90A-AW2TJ)	CH280CFAUL2	58	35	50	140	
5IK90GE-AW2U (5IK90A-AW2U)	5IK90GE-AW2TU (5IK90A-AW2TU)	CH200CFAUL2	58	29	41	95	Included
5IK90GE-CW2J (5IK90A-CW2J)	5IK90GE-CW2TJ (5IK90A-CW2TJ)	CH70BFAUL	58	35	50	130	Included
5IK90GE-CW2E (5IK90A-CW2E)	5IK90GE-CW2TE (5IK90A-CW2TE)	CH60BFAUL	58	29	41	85	

# Connection Diagrams

•The direction of motor rotation is as viewed from the shaft end of the motor. CW represents the clockwise direction, while CCW represents the counterclockwise direction.

•Connection diagrams are also valid for the equivalent round shaft type.

●Specify the type of the capacitor to be included by entering J, U or E in the box (□) within the model name.

Lead W	ire Type	Terminal Box Type								
5IK90GE-AW2 5IK90GE-CW2	5IK90GE-SW2	5IK90GE-AW2T□ 5IK90GE-CW2T□	5IK90GE-SW2T 5IK90GE-UT4F							
Clockwise	Clockwise L1(R) L2(S) L3(T) CW CW CW CW CW CW CW CW CW CW	Clockwise	Clockwise L1(R)° L2(S)° L3(T)° PE							
	Counterclockwise		Counterclockwise							
Counterclockwise	To change the rotation direction, change any two connections between R, S and T.	Counterclockwise	To change the rotation direction, change any two connections between U, V and W.							
Lo Red No Capacitor		Lo (2) Motor No (1) Capacitor PE								

PE: Protective Earth

Note:

Change the direction of single-phase motor rotation only after bringing the motor to a stop.

If an attempt is made to change the direction of rotation while the motor is rotating, motor may ignore reversing command or change its direction of rotation after some delay.

World K Series

1 W / 3 W

W 9